

Shape variations of spherical shell microemulsion using Neutron Spin Echo

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Outline

- Surfactants
- Why spin echo?
- Neutron Spin Echo
 - Principle
 - Instrumentation
- Data Reduction
- Data Analysis
- Summary

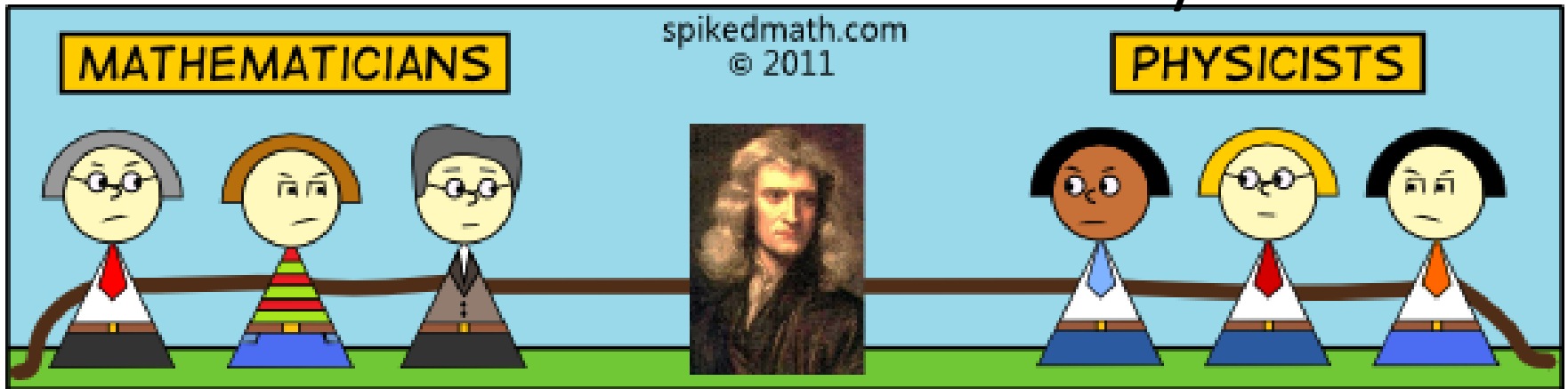
Blind dates



Mathematicians

vs

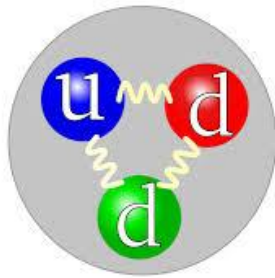
Physicists



Neutrons

vs

X-Rays



Surfactants – the molecular ice breaker

hydrophobic tail group

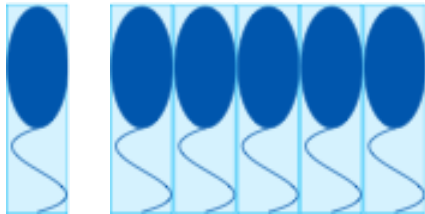
hydrophilic head group

Reduces interfacial tension



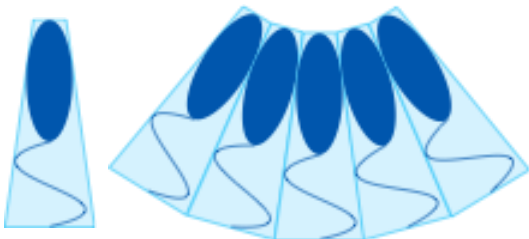
micelles

$$c_0 > 0$$



lamellae

$$c_0 = 0$$

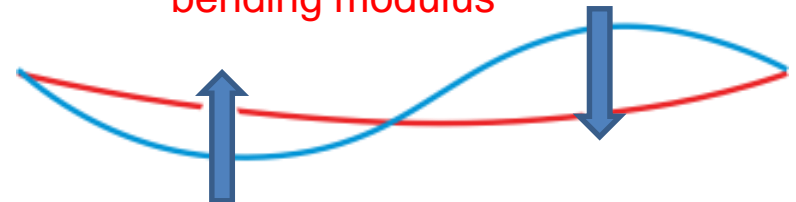


inverse micelles

$$c_0 < 0$$

$$f_{bend} = 2k \left(\frac{c_1 + c_2}{2} - c_0 \right)^2$$

bending modulus



Surfactants – the molecular ice breaker

hydrophobic tail group

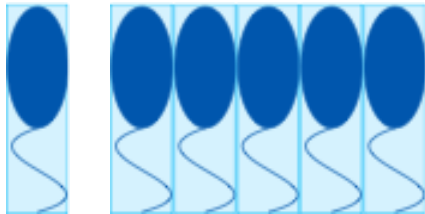
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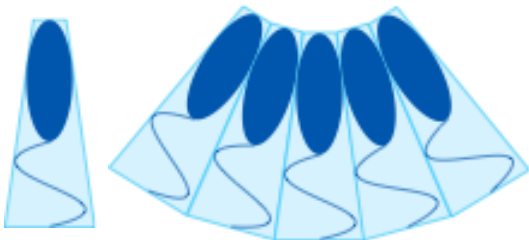
micelles

$$c_0 > 0$$



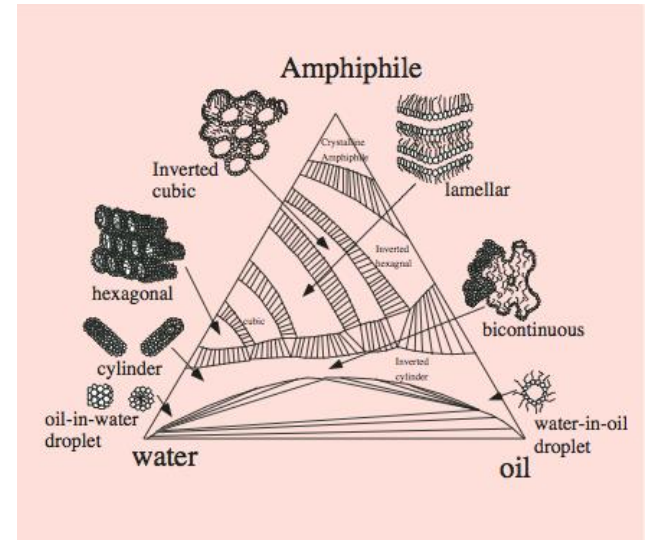
lamellae

$$c_0 = 0$$



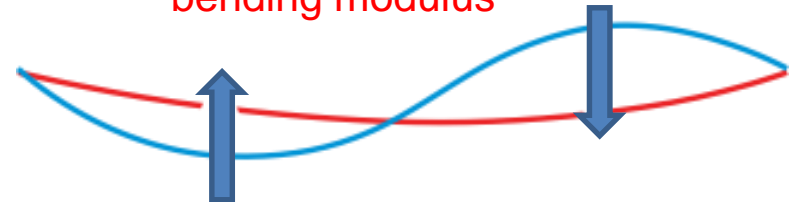
inverse micelles

$$c_0 < 0$$

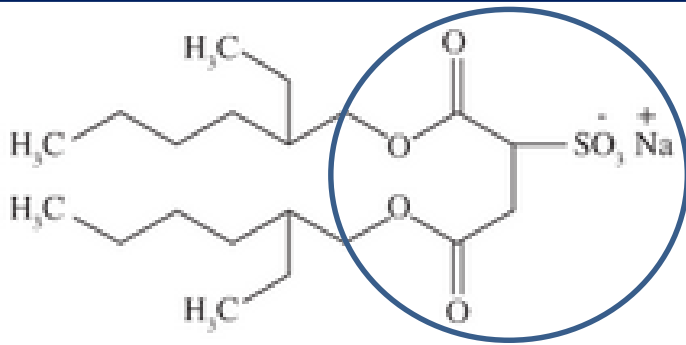


$$f_{bend} = 2k \left(\frac{c_1 + c_2}{2} - c_0 \right)^2$$

bending modulus

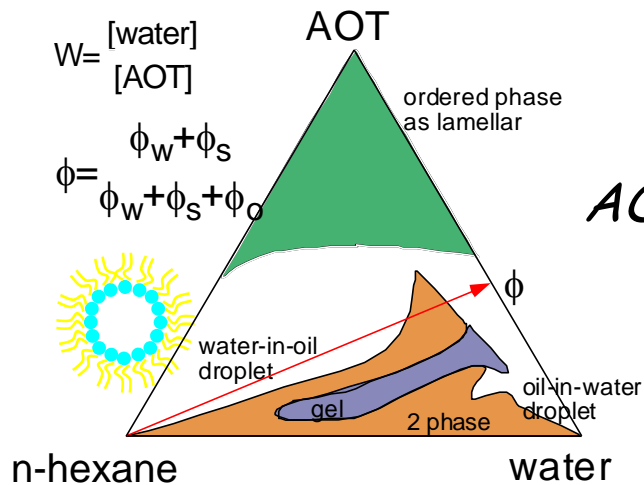


The system of interest



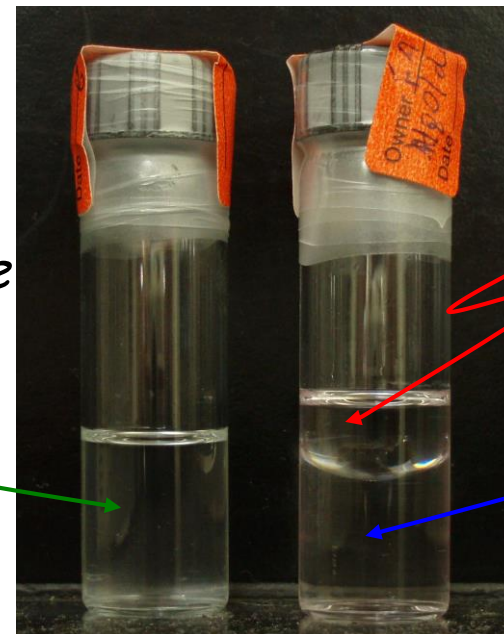
Diocetyl sodium sulfosuccinate (AOT)

AOT ($C_{20}H_{37}O_7SNa$): 5.1 vol.%
D₂O: 2.5 vol.%
d-hexane (C_6D_{14}): 92.4 vol.%



Kotlarchyk et al., *Phys. Rev. A* **29**, 2054 (1984).

AOT/water/hexane

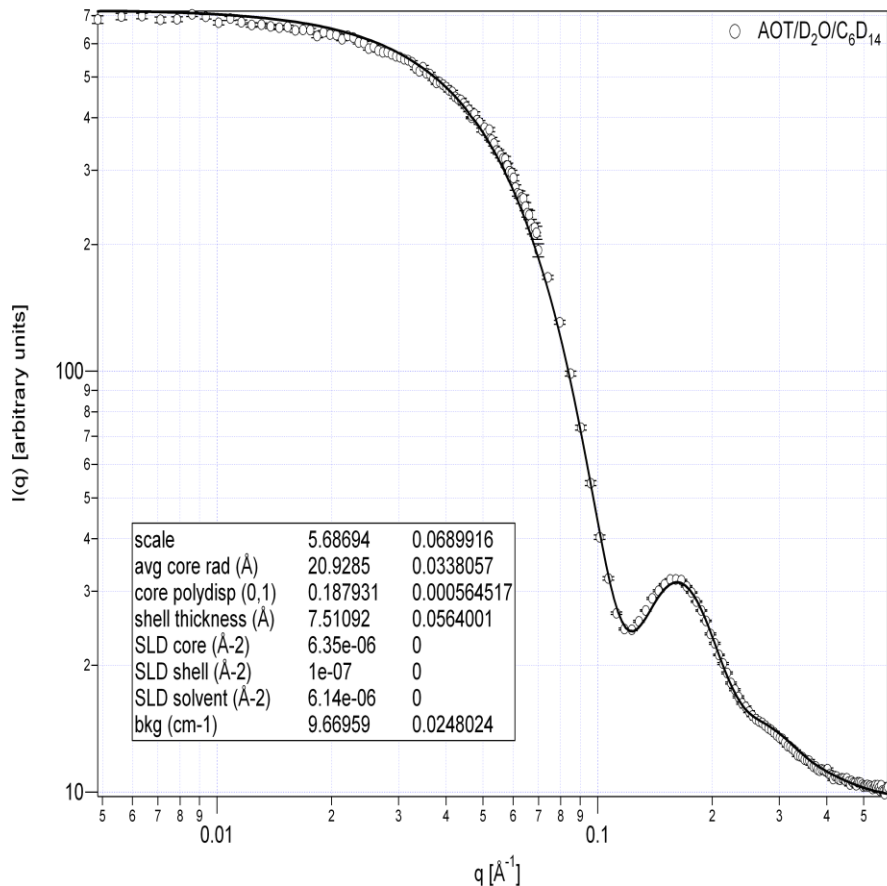


hexane

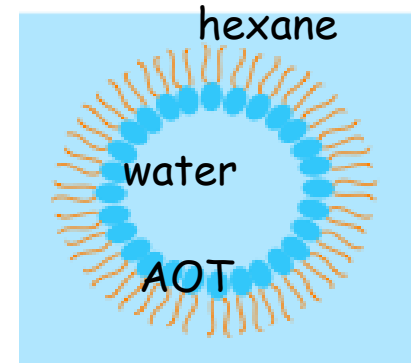
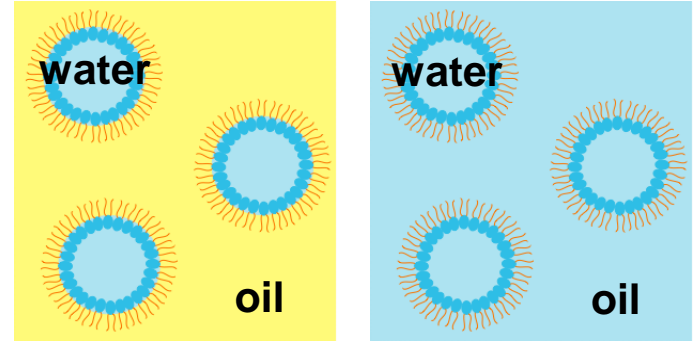
water

How to study microemulsions

static structure-from SANS



bulk contrast film contrast



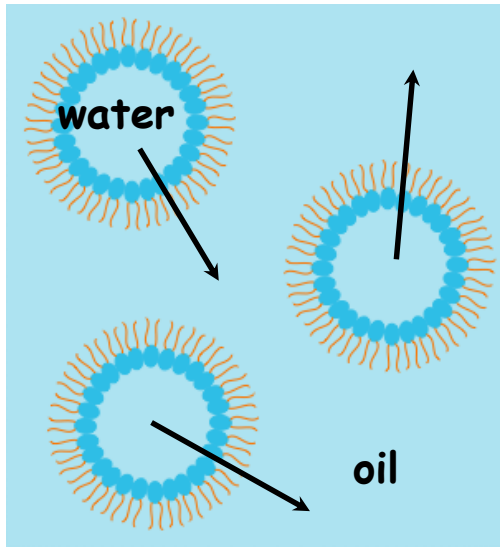
$$R_{\text{core}} = 20.9 \text{ \AA}$$

$$\text{Shell thickness} = 7.5 \text{ \AA}$$

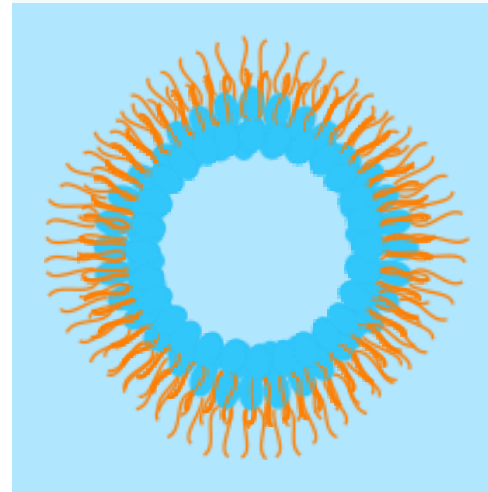
$$\text{Core polydispersity} = 0.19$$

How to study microemulsions

Dynamic structure



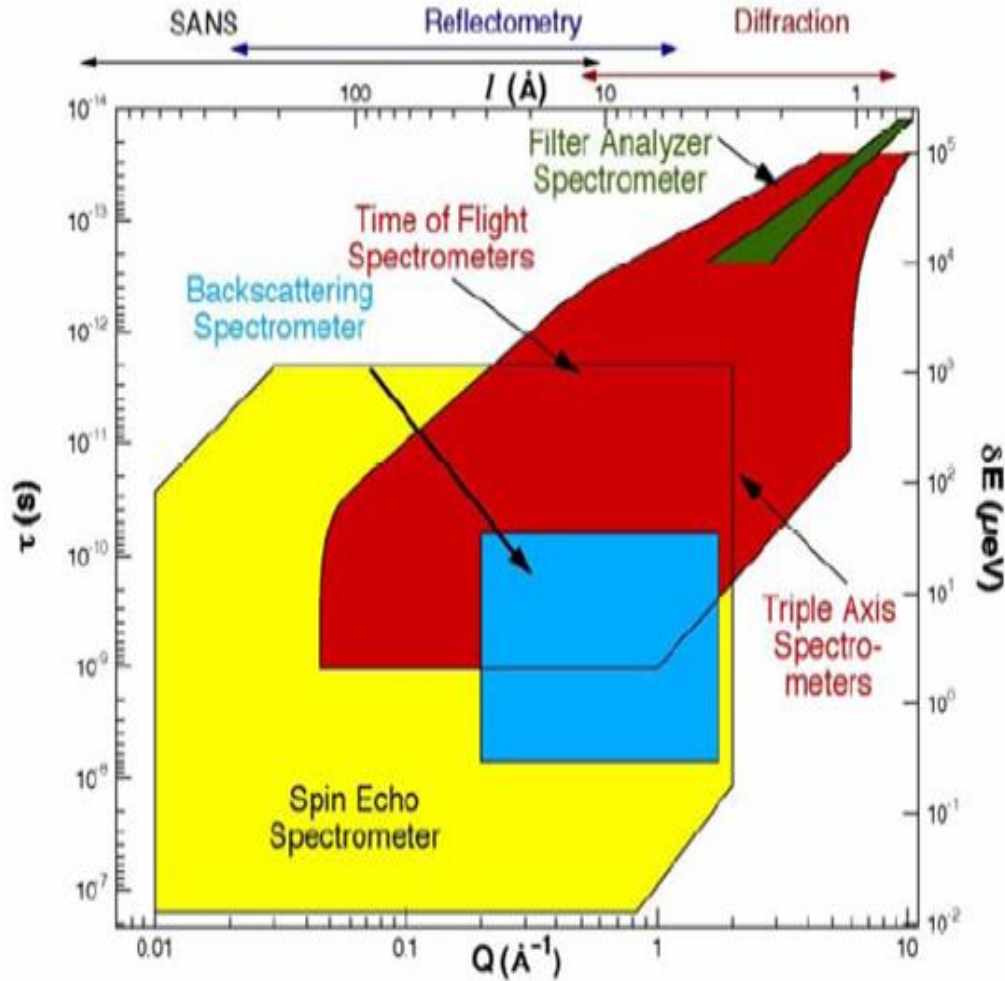
Translational diffusion



Shape fluctuation

So we need a technique that can measure both on length scale and time scale

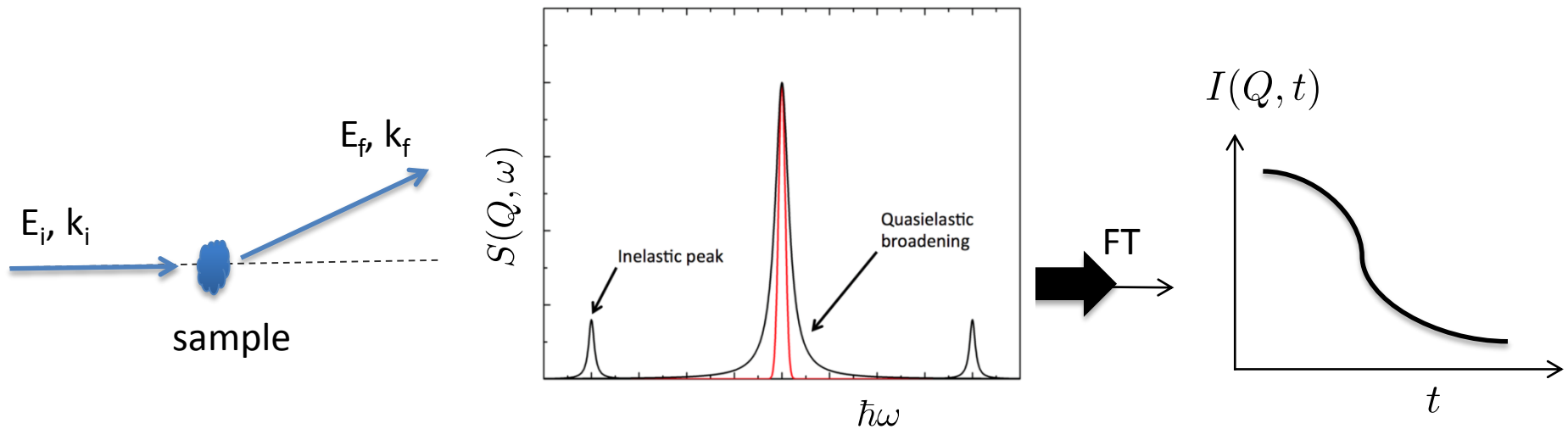
What are NSE advantages?



Larger length scale

Larger time scale

The “Special” Instrument: Neutron Spin Echo



NSE directly measures the intermediate scattering function in time domain!

The Idea of NSE: Precession of Spin

Neutron Properties

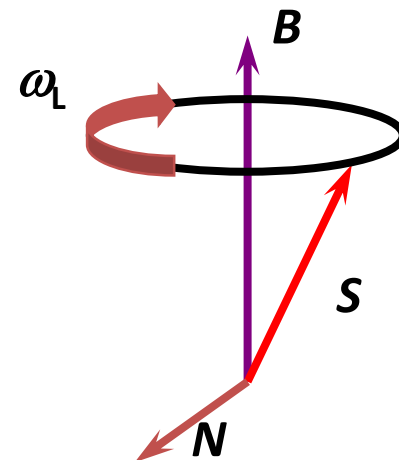
- Spin, $S = 1/2 \hbar$
- Gyromagnetic ratio $\gamma = g_n \mu_n / \hbar$

Torque in a magnetic field:

$$\mathbf{N} = \mathbf{S} \times \mathbf{B}$$

Larmor Precession Frequency:

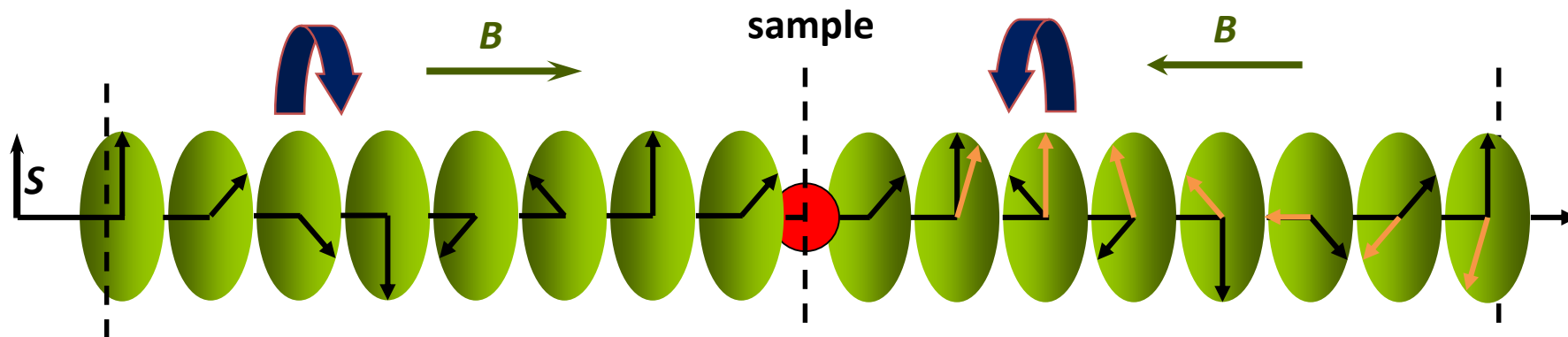
$$\omega_L = \gamma B$$



Larmor Precession

- elastic scattering

- quasi-elastic scattering



Encoding neutron velocity (energy) into spin orientation!

$I(Q, t)$ from Polarization Measurement

Quasi-Elastic scattering

Phase angle difference $\varphi \approx \gamma \frac{m^2 \lambda^{-3}}{2\pi h^2} J_0 \omega + \gamma \frac{m}{h} (J_0 - J_1) \lambda$

Polarization

$$P_x = \langle \cos(\varphi) \rangle = \int f(\lambda) \cos \left[\gamma \frac{m}{h} (J_0 - J_1) \lambda \right] d\lambda \times \int S(Q, \omega) \cos \left[\gamma \frac{m^2 \lambda^{-3}}{2\pi h^2} J_0 \omega \right] d\omega$$

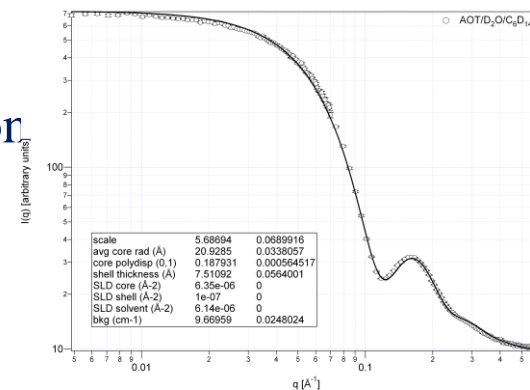
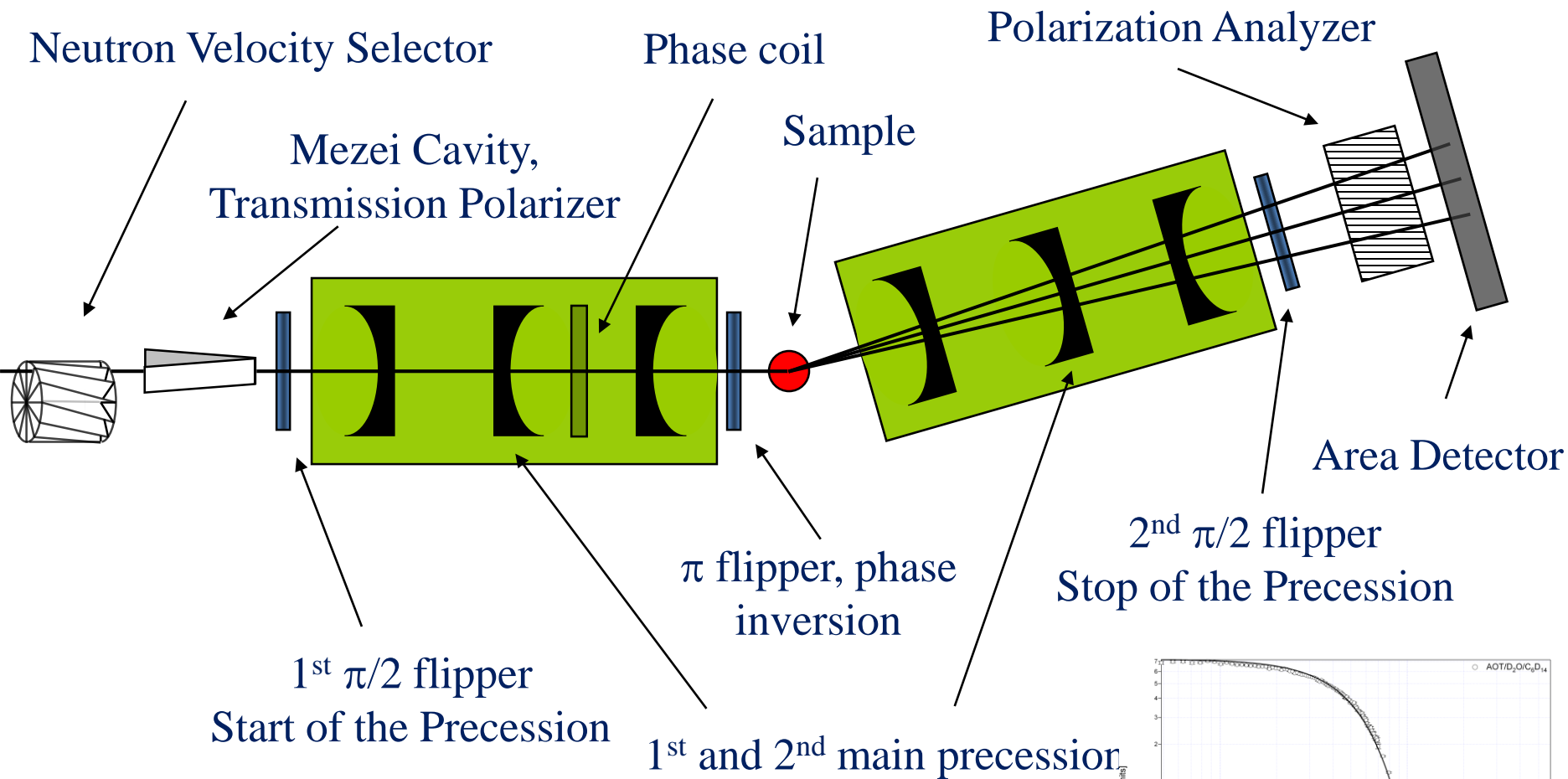
FT of the wavelength distribution \times FT of the Dynamic Structure Factor

Fourier time $t = \gamma \frac{m^2 \lambda^{-3}}{2\pi h^2} J_0 \lambda$

$$P_x(DJ^{pb_i}, Q, t) = P_s(DJ^{pb_i}) \int S(Q, \omega) \cos[\omega t] d\omega = P_s(DJ^{pb_i}) I(Q, t)$$

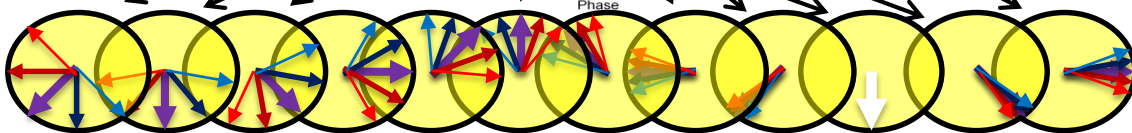
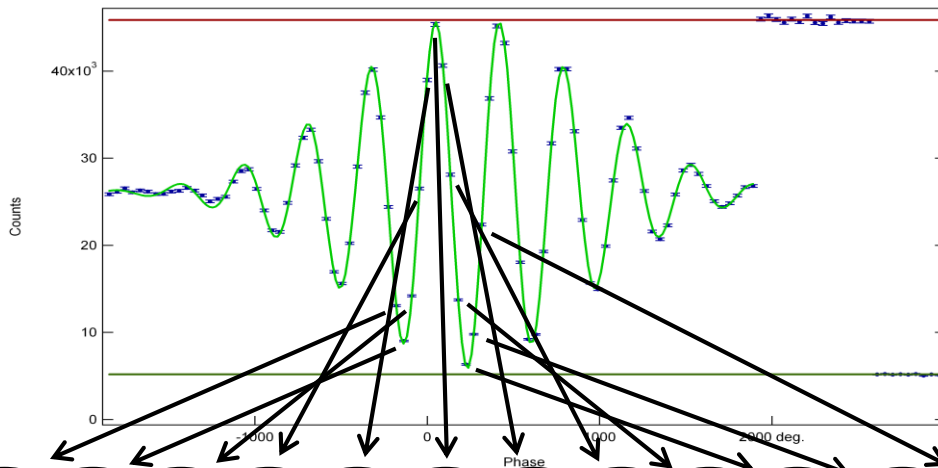
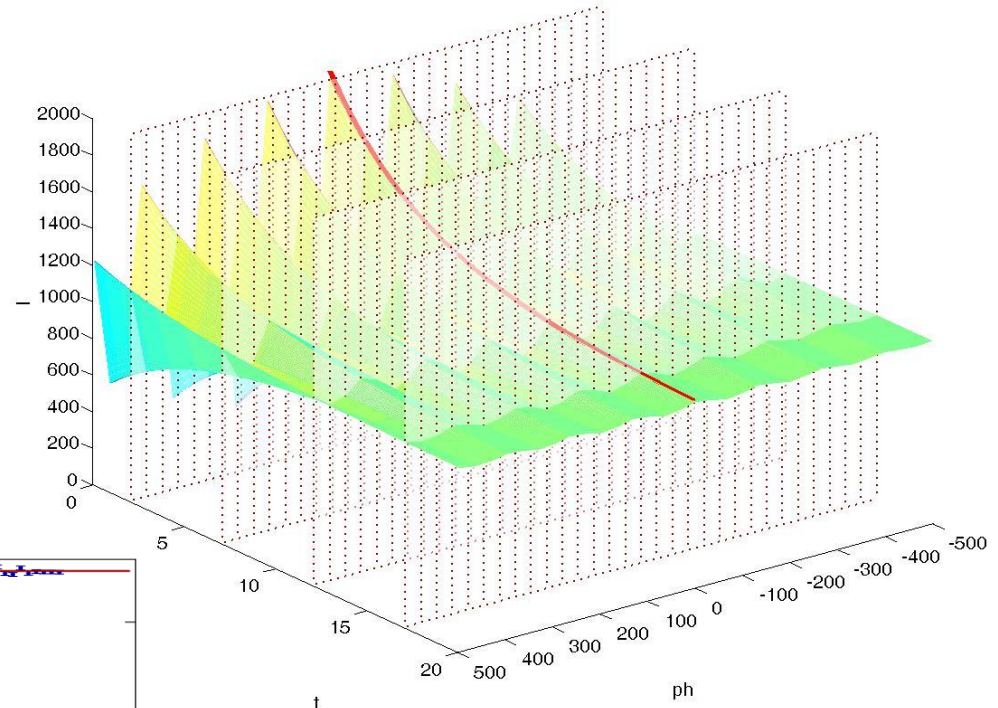
NSE measures the Fourier Transform of the Dynamic Structure Factor, namely, the Intermediate Scattering Function.

NSE: Instrumental Setup



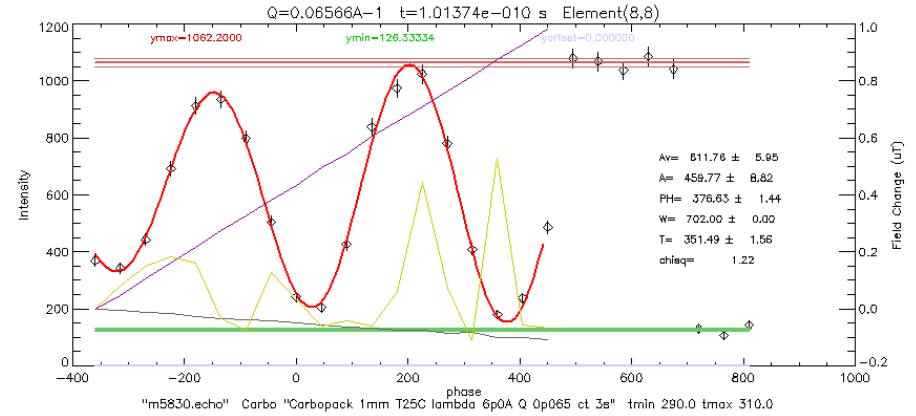
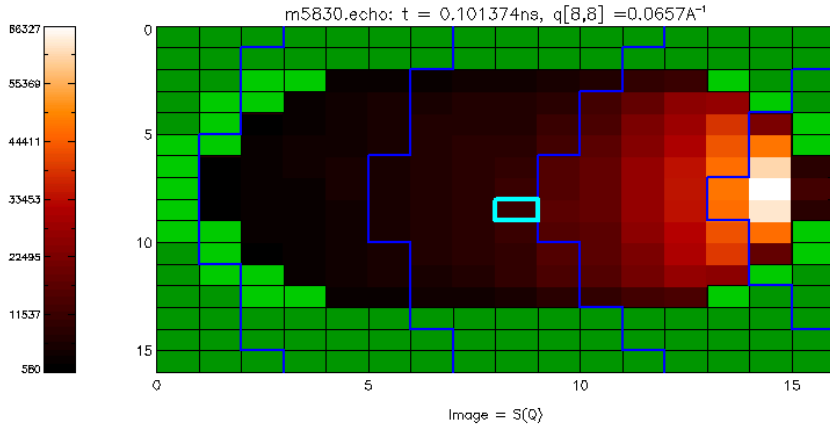
Polarization & Phase for Range of Q and Fourier Time

Polarization
Intensity vs. Phase
vs. Fourier Time

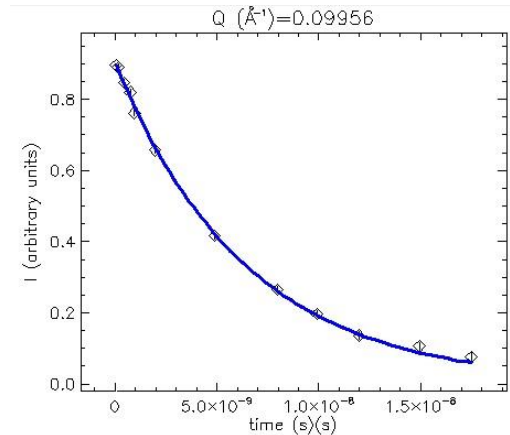


Polarization
Intensity vs. Phase

Physical Information Embedded in 2D Detector



- 2D Detector
- Each pixel encodes an echo
- $I(Q,t)$ calculated pixel by pixel and averaged by Q value



$$\frac{I(Q,t)}{I(Q)} = \frac{2 \left[A - (1-\phi) \frac{T}{T^{BKG}} A^{BKG} \right]}{2A^R / (Up^R - Dwn^R)} \left/ \left[(Up - Dwn) - (1-\phi) \frac{T}{T^{BKG}} (Up^{BKG} - Dwn^{BKG}) \right] \right.$$

Data Analysis

Full Cumulant Expansion

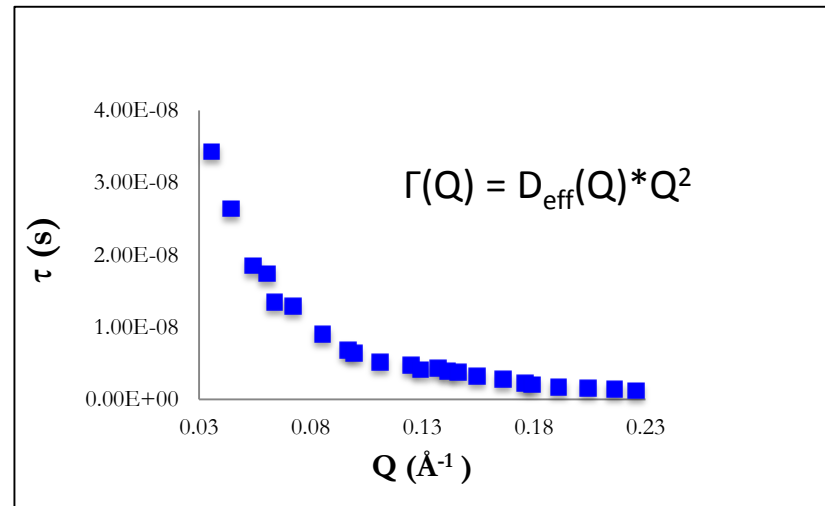
$$\frac{I(Q,t)}{I(Q,0)} = \exp\left[-c_1(Q)t + \frac{c_2(Q)t^2}{2!} + \frac{c_3(Q)t^3}{3!} + \dots\right]$$

First Cumulant Expansion

$$\frac{I(Q,t)}{I(Q,0)} = \exp\left[-D_{eff}(Q)Q^2t\right]$$

$$D_{eff}(Q) = D_0 \frac{1}{S(Q)}$$

T	298	K
K_B	1.38E-23	m ² kg/s ² K
ρ	0.188	
η	0.31	cP
η'	1.096	cP
R_0	26.8	Å



Data Analysis

Effective Diffusion Coefficient = D_{eff}

$$D_{def}(Q) = \frac{5/2 f_2(QR_0) \langle |a_2|^2 \rangle}{Q^2 \left\{ 4\rho \hat{e} j_0(QR_0) \hat{e}^2 + 5f_2(QR_0) \langle |a_2|^2 \rangle \right\}}$$

$$D_{eff} = D_{tr} + D_{def}$$

Hydrodynamic Limit: ($Q \rightarrow 0$): $D_{eff} = D_{tr}$

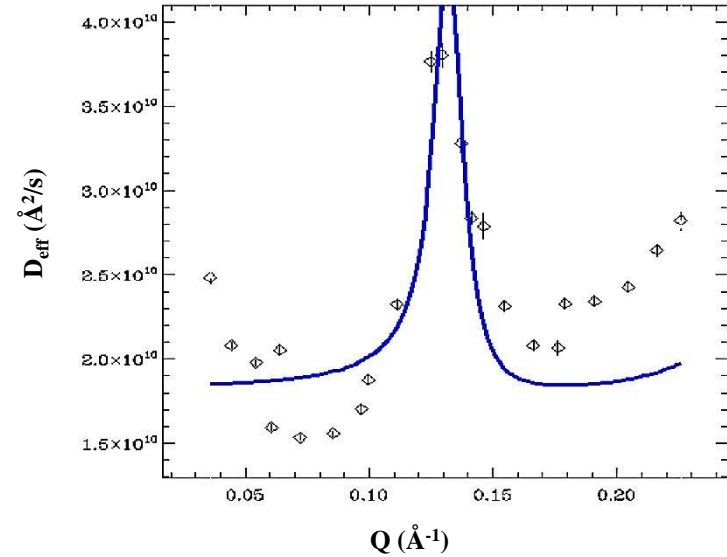
λ_2	4.39E+08	s-1
D_0	1.84E+10	$\text{\AA}^2/\text{s}$
R_0	23.4	\AA

Stokes-Einstein Equation

$$D_0 = \frac{k_B T}{6\pi\eta R_H}$$

$$R_H = 38.17 \text{ \AA}$$

$\frac{R_H}{R_g}$	Theoretical Value	Experimental Value
	1.29	1.42



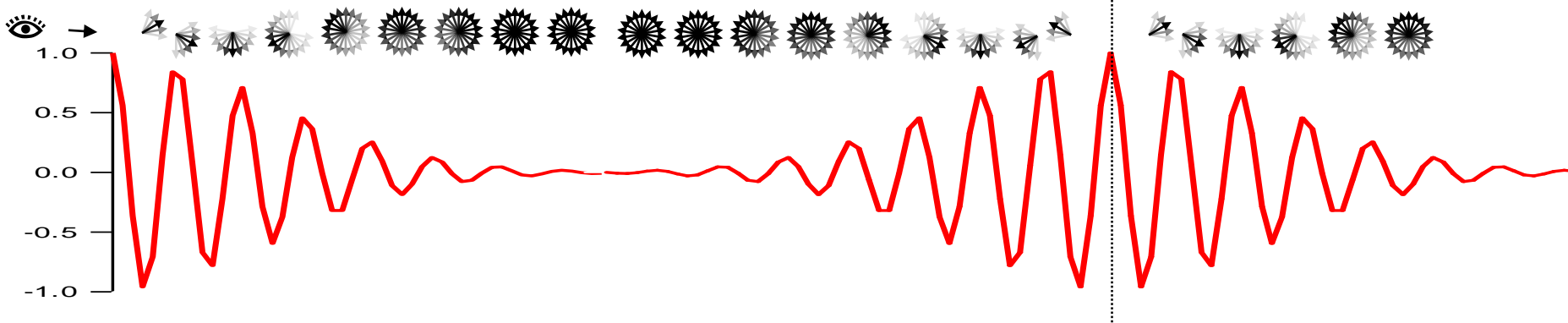
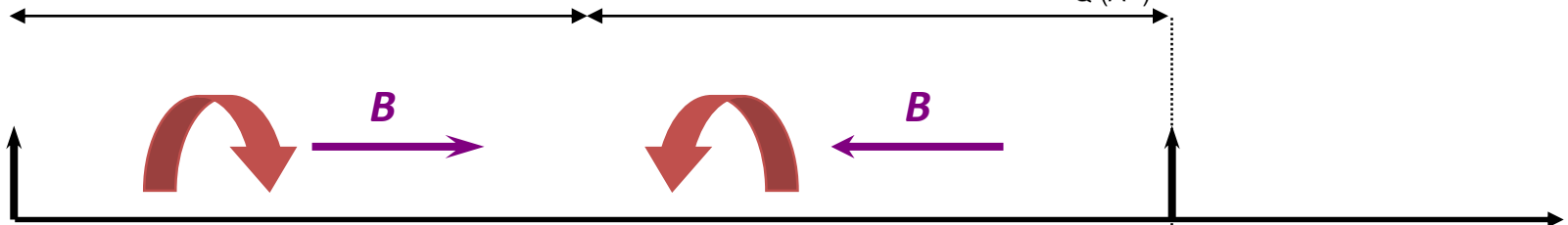
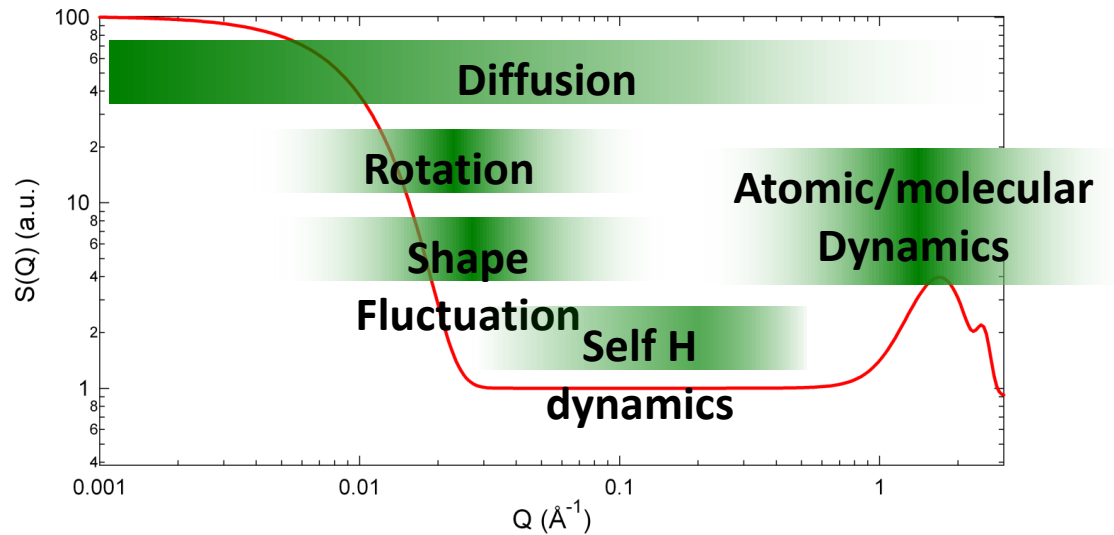
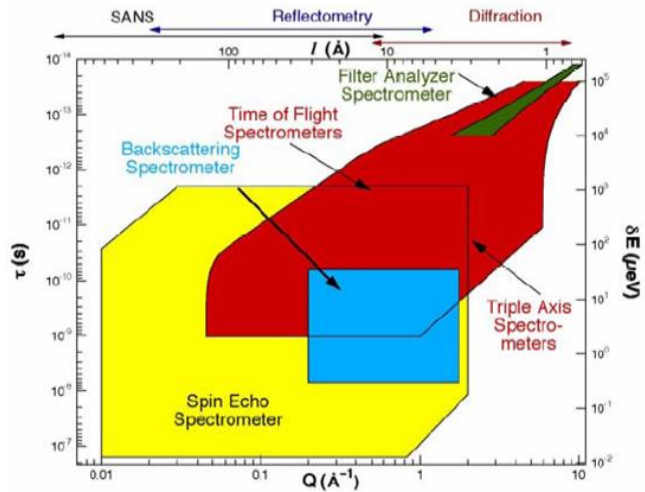
Bending Modulus of Elasticity

$$k = \frac{1}{48} \frac{k_B T}{\rho p^2} + \frac{1}{2} h R_0^3 \frac{23h' + 32h}{3h}$$

$$k = 0.69 K_B T$$

Thermally Active

Summary



Thank You!

