

# *Introduction to Neutron Spin Echo Spectroscopy*

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Methods and Applications of SANS, NR, and NSE  
NCNR, June 18th – 23rd, 2012

## *Outline*

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- History
- Dynamic Neutron Scattering (Recap)
- The principles of Neutron Spin Echo
- Instrumental Setup of Neutron Spin Echo
- Conclusion

## The beginning

### Neutron Spin Echo: A New Concept in Polarized Thermal Neutron Techniques

F. Mezei

Institut Laue-Langevin, Grenoble, France\* and  
Central Research Institute for Physics, Budapest, Hungary

Received July 7, 1972

A simple method to change and keep track of neutron beam polarization non-parallel to the magnetic field is described. It makes possible the establishment of a new focusing effect we call neutron spin echo. The technique developed and tested experimentally can be applied in several novel ways, e.g. for neutron spin flipper of superior characteristics, for a very high resolution spectrometer for direct determination of the Fourier transform of the scattering function, for generalised polarization analysis and for the measurement of neutron particle properties with significantly improved precision.

F. Mezei, *Z. Physik.* **255**, 146 (1972).

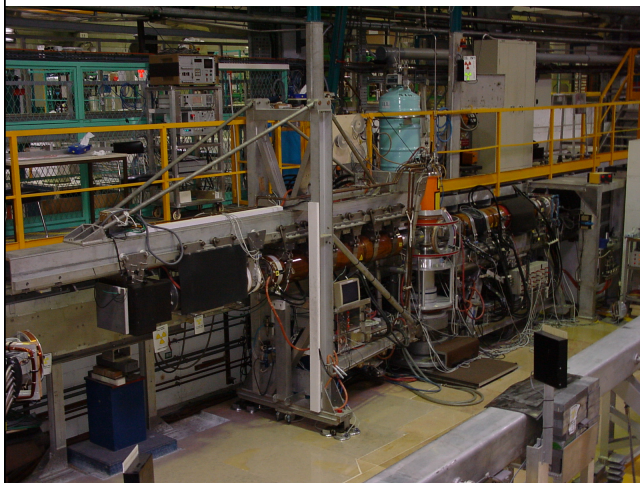
## NSE Today in the World

Physical Map of the World, April 2004



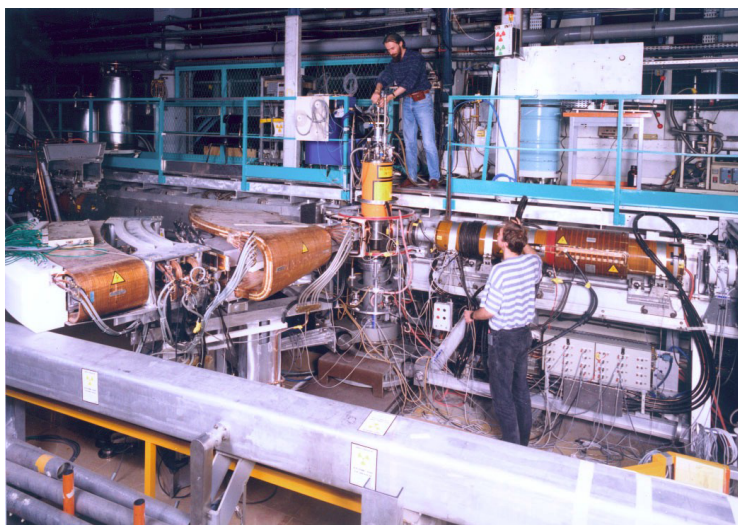
+ NSE option for triple-axis spectrometers  
+ developing ones

## *What does a NSE Spectrometer Look Like?*



IN-11 @ ILL  
The first

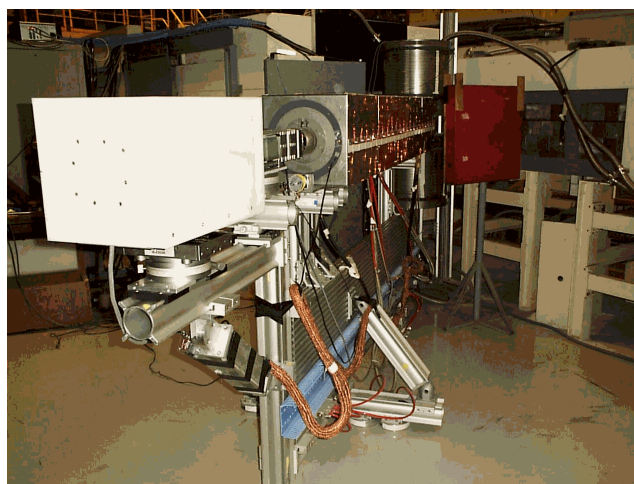
## IN-11c @ ILL; Wide Detector Option



IN-15 @ ILL

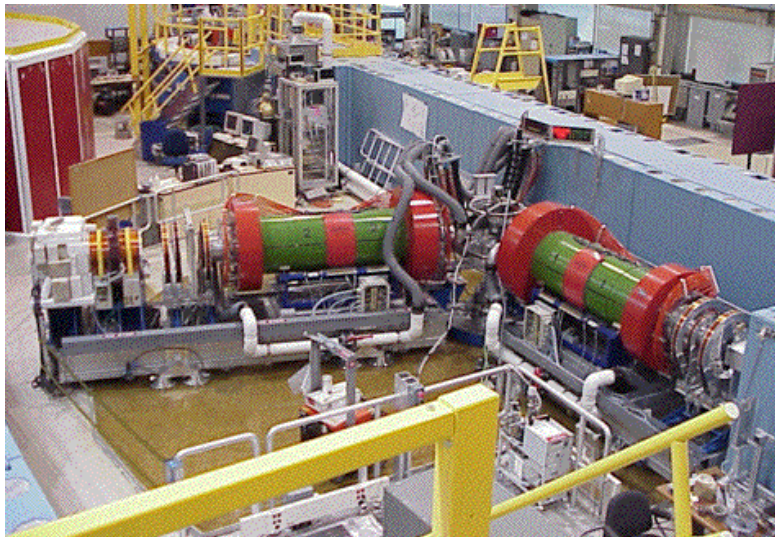


MUSES, Resonance Spin Echo @ LLB





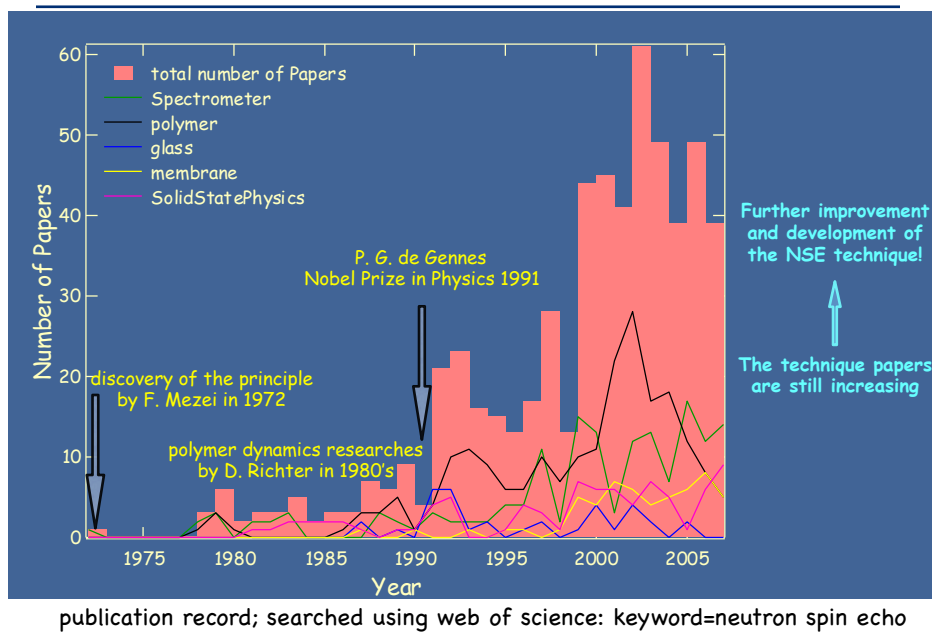
NSE @ NCNR



NSE @ SNS

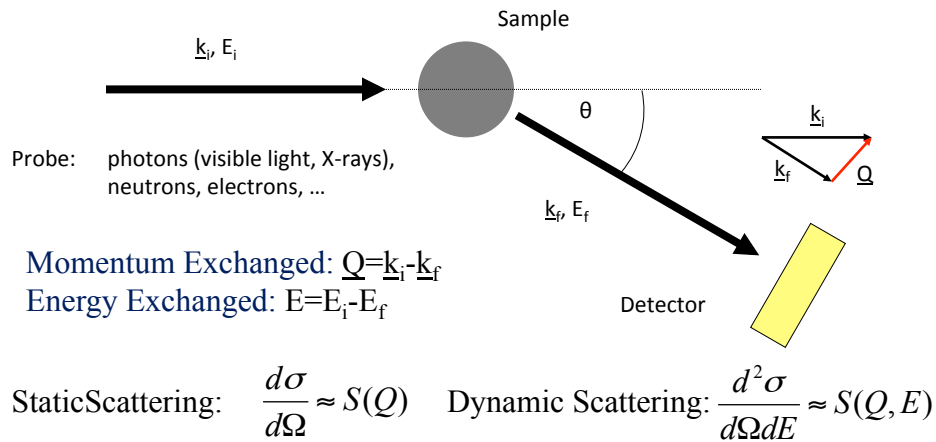


## NSE Publications



*Dynamic Neutron Scattering*

## Static and Dynamic Scattering



## Static and Dynamic Scattering

$$S(Q) = FT_S \left\{ \left\langle \exp[-i\underline{Q}(\underline{r}_i - \underline{r}_j)] \right\rangle \right\}$$

Fourier Transform of the Space  
Correlation Function

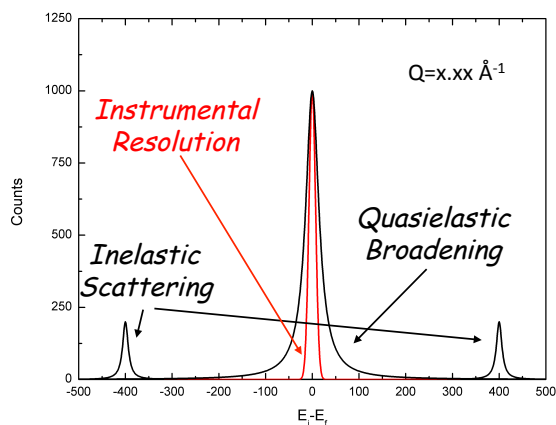
$$S(Q, E) = FT_T \left\{ \left\langle \exp[-i\underline{Q}(\underline{r}(t) - \underline{r}(0))] \right\rangle \right\} = FT_T \{ I(Q, t) \} = FT_{ST} \{ G(r, t) \}$$

Fourier Transform of the Space-Time  
Correlation Function

$I(Q, t)$  Intermediate Scattering Function (ISF)

$G(r, t)$  van Hove Correlation Function

## $S(Q,E)$



### Inelastic Scattering

**excitation:** neutrons exchange energy with an oscillatory motion which has a finite energy transfer  
Ex: phonon, magnon, ...

### Quasielastic Scattering

**relaxation:** neutrons exchange energy with random motion which makes another new equilibrium state (no typical finite energy transfer exists)  
Ex.: rotation, vibration, diffusion...

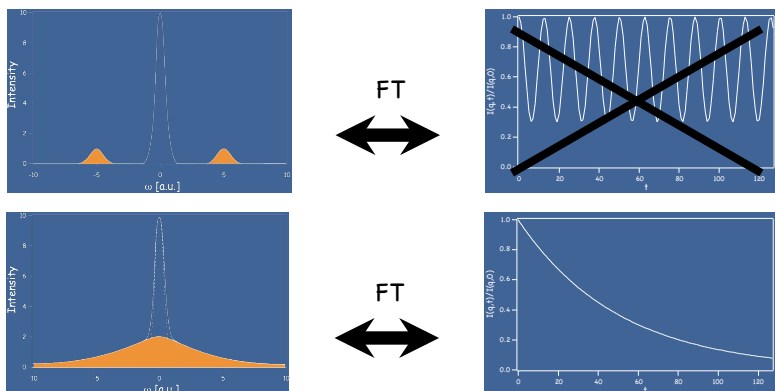
**Thermally Activated Motions Takes Place in the System.**

## Energy and Time Domain

NSE works in the TIME domain

NSE measures the Normalized Intermediate Scattering

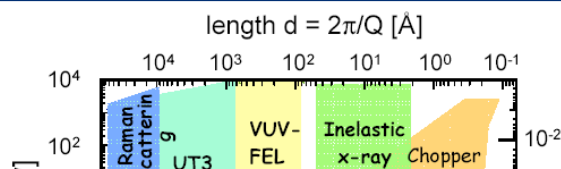
Function:  $I(Q,t)/I(Q,0)$



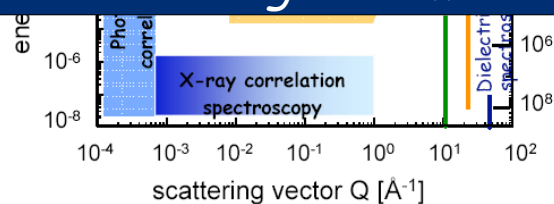
**NSE Deals Almost Exclusively with Quasielastic Scattering**



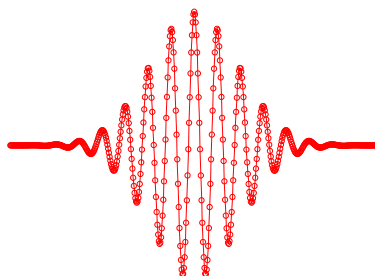
## Dynamic Neutron Scattering



*NSE is the neutron scattering techniques that gives access to the largest length-scales and longest time scales*



*Neutron Spin Echo  
Principle of Operation*



## The Idea of Neutron Spin Echo

NSE Breaks the Relationship between Intensity & Resolution

- Traditional Instruments - define *both* incident & scattered wavevectors in order to define  $E$  and  $Q$  accurately
- Traditional Instruments - use collimators, monochromators, choppers etc to define both  $\underline{k}_i$  and  $\underline{k}_f$
- NSE - measure the *difference* between appropriate components of  $\underline{k}_i$  and  $\underline{k}_f$  (original use: measure  $\underline{k}_i - \underline{k}_f$  i.e. energy change)
- NSE - use the neutron's spin polarization to encode the difference between components of  $\underline{k}_i$  and  $\underline{k}_f$
- NSE - can use large beam divergence &/or poor monochromatization to increase signal intensity, while maintaining very good resolution

## Neutron Precession

### Neutron Properties

- Mass,  $m_n = 1.675 \times 10^{-27}$  kg
- Spin,  $S = 1/2$  [in units of  $h/(2\pi)$ ]
- Gyromagnetic ratio  $\gamma = g_n \mu_n / [h/(2\pi)] = 1.832 \times 10^8 \text{ s}^{-1} \text{ T}^{-1}$  (29.164 MHz T<sup>-1</sup>)

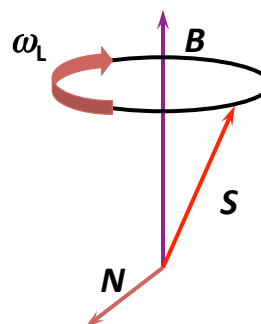
### In a Magnetic Field

- The neutron experiences a torque from a magnetic field  $B$  perpendicular to its spin direction.

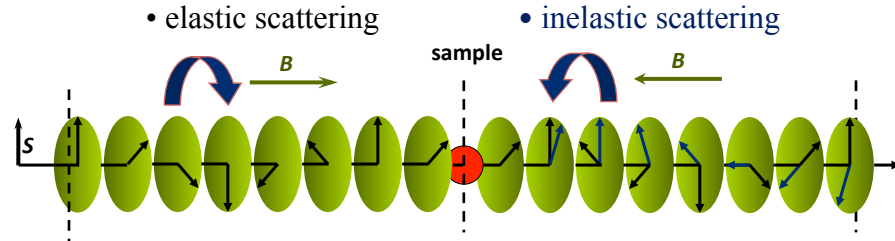
$$\longrightarrow N = S \times B$$

- Precession with the Larmor frequency:

$$\longrightarrow \omega_L = \gamma B$$



## Scattering Event: Single Neutron

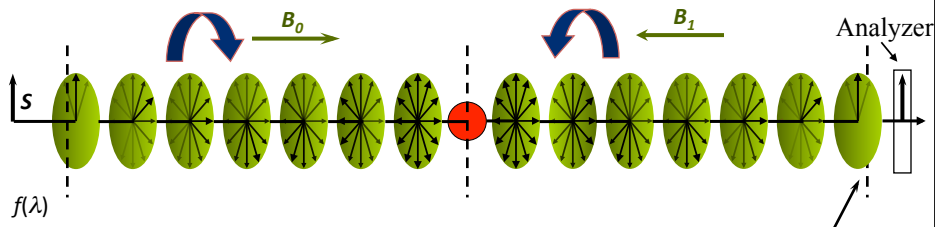


$$\varphi = \gamma \int \frac{Bdl}{v} \quad \Delta\varphi = \gamma \left( \frac{1}{v} - \frac{1}{v'} \right) \int Bdl = \frac{\gamma \Delta v}{v^2} \int Bdl = \frac{m\lambda}{h} \frac{\gamma \Delta v}{v} \int Bdl$$

$$NT(\lambda) = \frac{1}{2\pi} \int \frac{\gamma B m \lambda}{h} dl = \frac{\gamma m \lambda}{2\pi h} \int Bdl = 7370 \times J [T \cdot m] \times \lambda [\text{\AA}]$$

$$J = \int Bdl \quad \boxed{J \text{ field integral. At NCNR: } J_{\max} = 0.5 \text{ T}\cdot\text{m}} \\ \boxed{NT(\lambda=8\text{\AA}) \approx 3 \times 10^5}$$

## Scattering Event: Neutron Beam



Elastic scattering

$$\bar{\varphi} = \left\langle \gamma \frac{\int B_0 dl}{v} - \gamma \frac{\int B_1 dl}{v} \right\rangle_{f(\lambda)}$$

$$P_x = 1 \quad \bar{\varphi} = 0$$

Again:

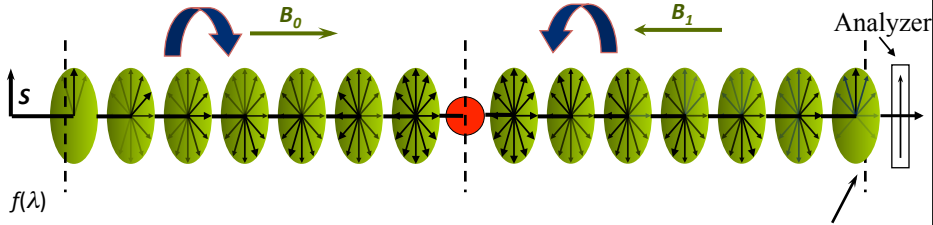
The measured quantity is the Polarization, i.e. the spin component along x:  $P_x = \langle \cos\varphi(\lambda) \rangle$ :

$$\text{Echo Condition: } J_0 = J_1$$

Note:

The requirement that  $\varphi=0$  can be in some cases released. This treatment is valid for the most common case of Quasi-Elastic Scattering

## Scattering Event: Neutron Beam



Quasi-Elastic scattering

Again:  
The measured quantity is the Polarization, i.e. the spin component along x:  $P_x = \langle \cos \varphi(\lambda) \rangle$ :

$$\varphi = \left\langle \gamma \frac{\int B_0 dl}{v(\lambda)} - \gamma \frac{\int B_1 dl}{v(\lambda) + \delta v} \right\rangle \xrightarrow{\text{Series Expansion in } \delta\lambda \text{ and } \delta J} \varphi = \gamma \frac{m}{h} J_0 \delta\lambda + \gamma \frac{m}{h} (J_0 - J_1) \lambda$$

phase

$$\hbar\omega = \Delta E = \frac{\hbar^2}{2m} \left[ \frac{1}{\lambda^2} - \frac{1}{(\lambda + \delta\lambda)^2} \right] \approx \frac{\hbar^2}{m} \frac{\delta\lambda}{\lambda^3}$$

$$\delta\lambda = \frac{\omega}{2\pi\hbar} m\lambda^3$$

$$\varphi = \gamma \frac{m^2 \lambda^3}{2\pi\hbar^2} J_0 \omega + \gamma \frac{m}{h} (J_0 - J_1) \lambda$$

0 at the echo condition

## The Basic Equations of NSE

$$P_x = \langle \cos(\varphi) \rangle = \iint f(\lambda) S(Q, \omega) \cos \left[ \gamma \frac{m^2 \lambda^3}{2\pi\hbar^2} J_0 \omega + \gamma \frac{m}{h} (J_0 - J_1) \lambda \right] d\lambda d\omega$$

$$P_x = \langle \cos(\varphi) \rangle = \int f(\lambda) \cos \left[ \gamma \frac{m}{h} (J_0 - J_1) \lambda \right] d\lambda \times \int S(Q, \omega) \cos \left[ \gamma \frac{m^2 \lambda^3}{2\pi\hbar^2} J_0 \omega \right] d\omega$$

FT of the wavelength distribution  
**Fourier time**

FT of the Dynamic Structure  
 $t = \gamma \frac{m^2 \lambda^3}{2\pi\hbar}$   
**Factor**

$$P_x(\Delta J^{ph}, Q, t) = P_s(\Delta J^{ph}) \int S(Q, \omega) \cos[\omega t] d\omega = P_s(\Delta J^{ph}) I(Q, t)$$

NSE measures the Fourier Transform of the Dynamic Structure Factor

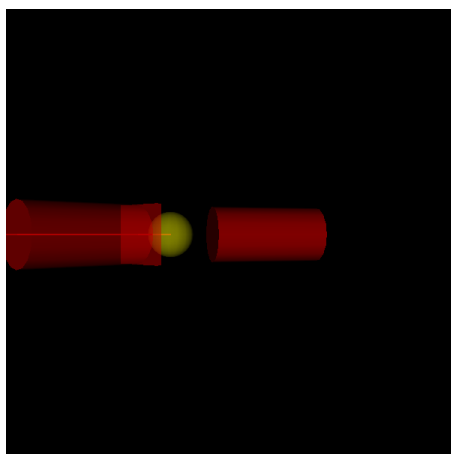


## *NSE principles: summary*

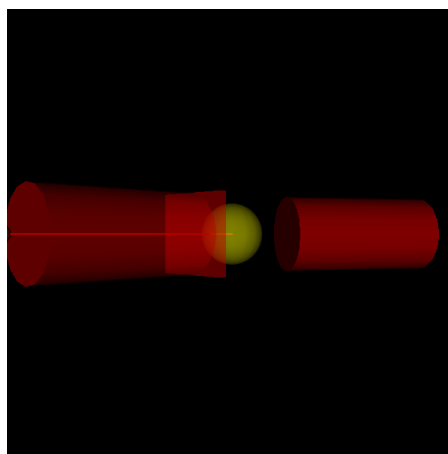
- Neutron Spin Echo Instruments are “machinery” which measure the Fourier transform of the Dynamic Structure Factor,  $S(Q, \omega)$ , i.e. the (normalized) Intermediate Scattering Function (ISF),  $I(Q, t)/I(Q, 0)$ .
- The neutrons’ velocity is encoded into their spin state.
  - The neutron beam goes through two equals homogeneous magnetic field paths before and after the sample.
  - Within the magnetic fields each neutrons’ spin performs a precession at a speed determined by the field intensity.
  - If the scattering event does not change the neutrons’ speed (elastic scattering), the initial polarization of the beam is recovered.
- The polarization of the scattered neutron beam is proportional to the ISF at a specific value of  $t$  determined by the strength of the precession field (and by the incident neutron wavelength).

## *NSE Effect*

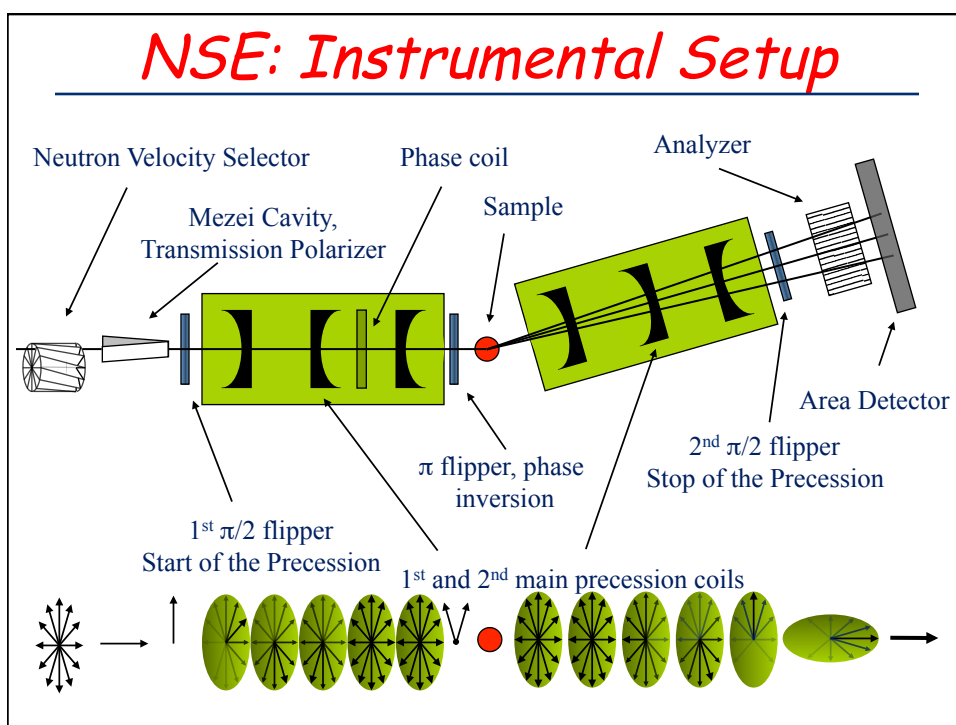
*Elastic Scattering*

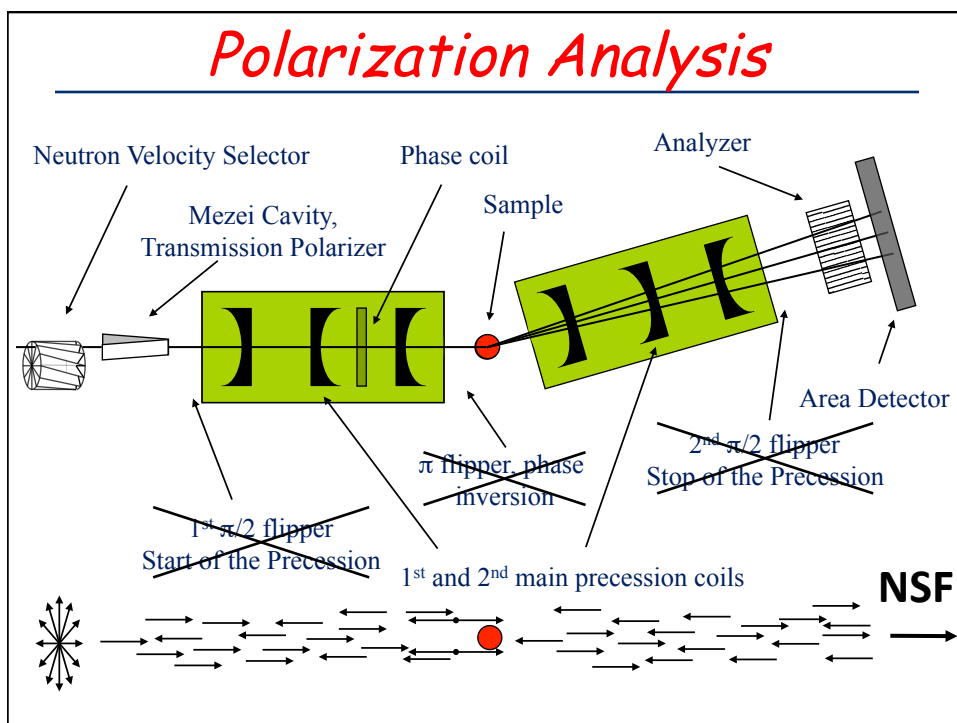
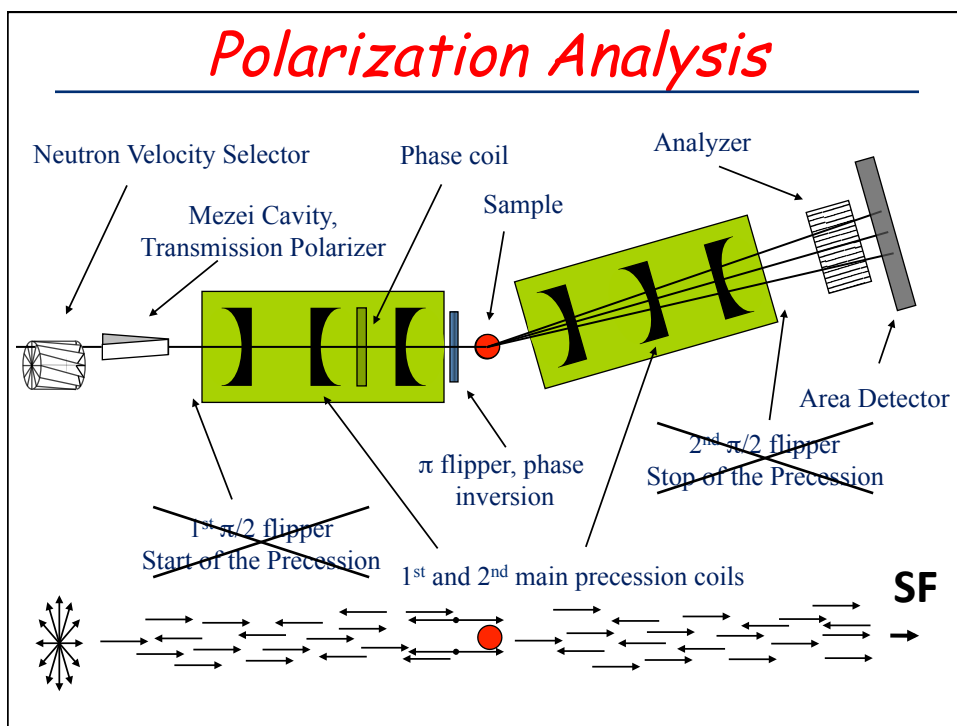


*QuasiElastic Scattering*



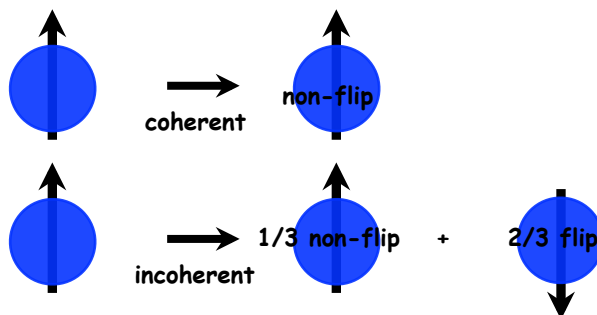
# Instrument Setup





## Nuclear Scattering Event and Neutron Moment

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## Nuclear Scattering Polarization Analysis

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If no magnetic scattering is present and the sample is isotropic, the three polarization directions,  $xyz$ , are equivalent:

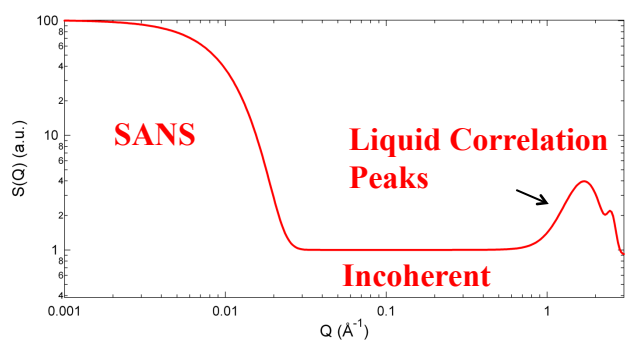
$$N^{incoh} = \frac{3}{2} SF$$

$$N^{coh} = NSF - \frac{1}{2} SF$$



## Structure Factor

The Structure Factor,  $S(Q)$ , is the most relevant information for the preparation and, later, interpretation of a NSE experiment.

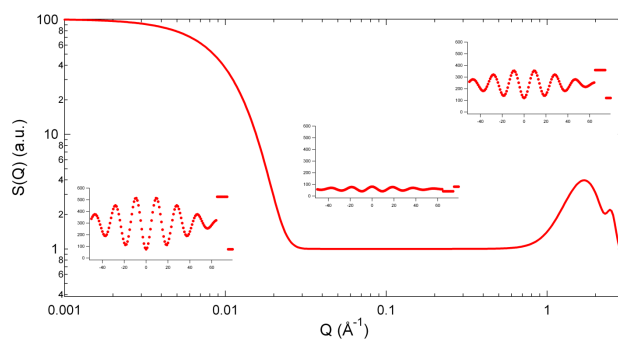


Nanoscale Object  $\longleftrightarrow$  Atoms

## NSE: Coherent vs Incoherent

NSE is known for the investigation of the coherent dynamics.

Incoherent scattering intensity is reduced to  $-1/3$  in NSE. The best achievable flipping ratio is 0.5.



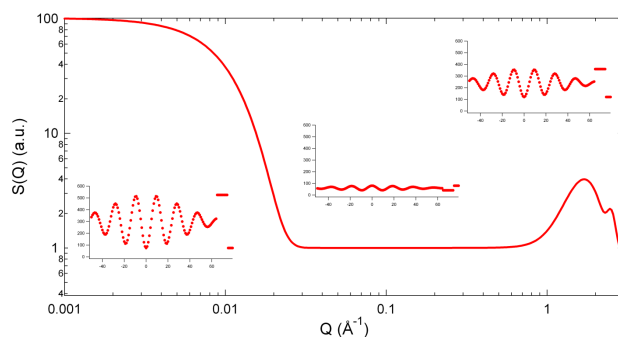
However, the main limitation to the study of incoherent scattering by NSE is the  $Q$  coverage of the instrument.

Recent advancements in NSE instrumentation aim to overcome this limitation (IN-11C, the WASP project).

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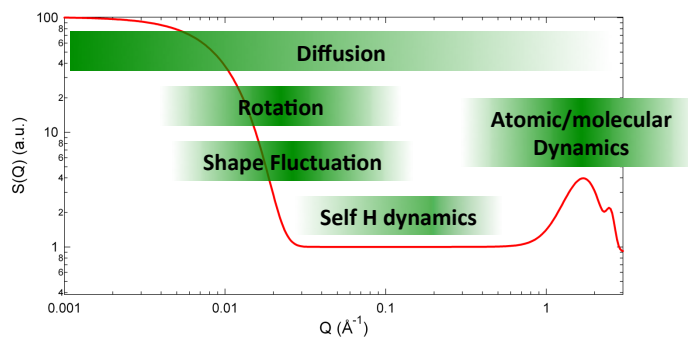
Most important is to avoid  $Q$  areas where coherent and incoherent intensity cancel each other.

## *The Intermediate Scattering Function*

NSE measures the time decay of the structures defining  $S(Q)$ :

$$\frac{I(Q,t)}{I(Q,0)} = \frac{\langle \exp\{-iQ[r_i(t) - r_j(0)]\} \rangle}{\langle \exp\{-iQ[r_i(0) - r_j(0)]\} \rangle}$$

## Types of Dynamics



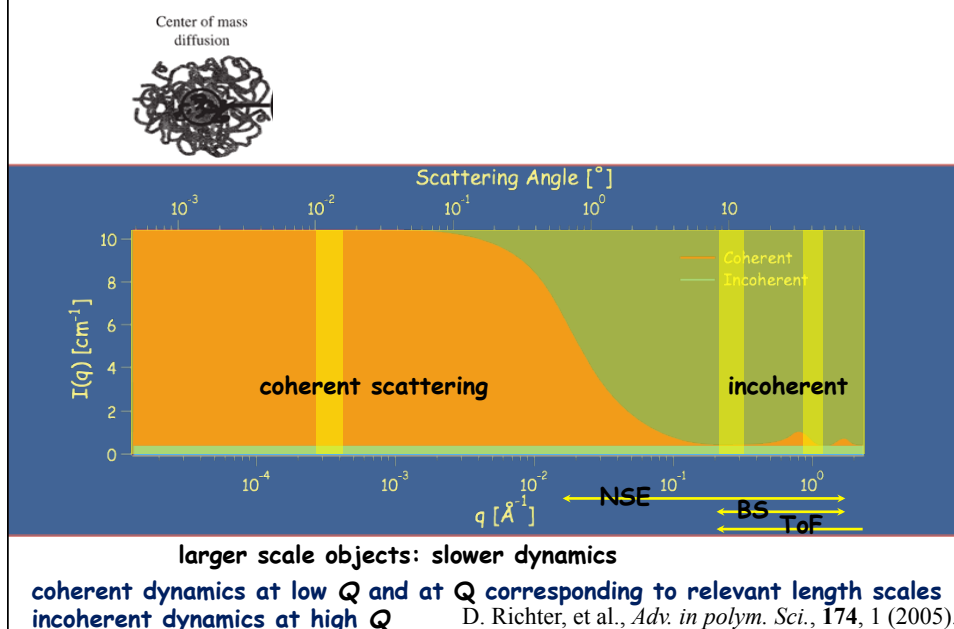
At length scales larger than the macromolecular size: Diffusion.

At length scales of the order the macromolecular size: Rotations and shape fluctuations.

Where the incoherent signal is dominant: Self H dynamics (translations, rotations, vibrations,...)

At the structural peaks: Atomic/Molecular Dynamics.

## Lengthscales of Polymer Dynamics



# Conclusions

## *Take home messages*

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- NSE studies dynamics in the ps to ns time range (4 orders of magnitude in time!), over lengthscales from tens of Ås to fractions of an Å. It covers the largest lengthscales and longest timescales of all neutron spectrometers.
- NSE works in the time domain. The instrumental resolution can be simply divided out.
- NSE works by encoding the neutron speed in its spin state. Do not depolarize the neutron beam.
- NSE is counting intensive. Large samples and/or significant scattering intensities are required.
- Good knowledge of the sample, in particular of its structure, is required for the preparation of the experiment and the understanding of the results.



## Further Readings

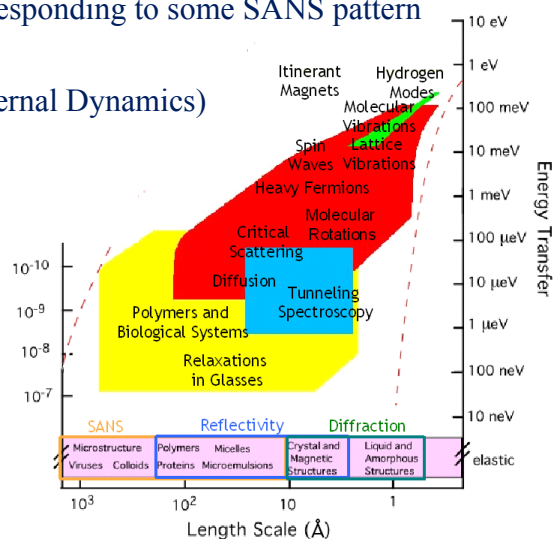
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- F. Mezei, C. Pappas, T. Gutberlet (Eds.): Neutron Spin-Echo Spectroscopy (2<sup>nd</sup> workshop), *Lecture Notes in Physics*, 601, Springer, Heidelberg, 2003.
- D. Richter, M. Monkenbusch, A. Arbe, and J. Colmenero, “Neutron spin echo in polymer systems” *Adv. in polym. Sci.*, **174**, 1 (2005).
- B. Farago, “Recent developments and applications of NSE in soft matter” *Curr. Opin. Colloid Interface Sci.*, **14**, 391 (2009).

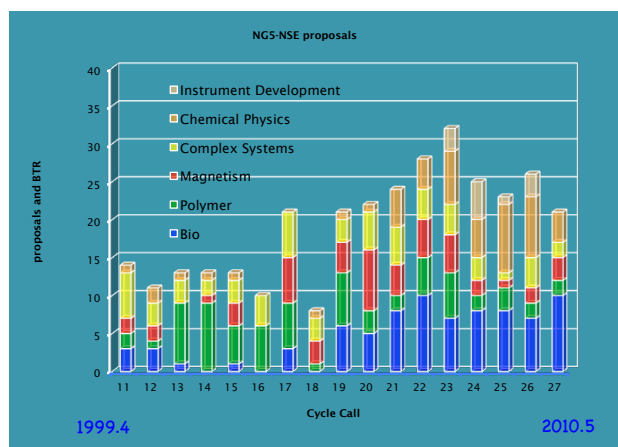
Final Remarks

## What Does NSE Study?

- Coherent Dynamics
  - Density Fluctuations corresponding to some SANS pattern
    - Diffusion
    - Shape Fluctuations (Internal Dynamics)
    - Polymer Dynamics
    - Glassy Systems
- Incoherent Dynamics
  - Self-Dynamics (H atoms)
- Magnetic Dynamics
  - Spin Glasses



## NG5 NSE proposal statistics



### Bio

model bio-membrane  
protein motion

### Polymer

segment dynamics  
hydrogels  
polymer complex

### Magnetism

frustrated magnets  
spin glass

### Chemical Physics

confined water  
ionic liquids

### Complex Fluids

microemulsions  
surfactant membranes  
cluster dynamics